

## Exam in Analytical Mechanics, 5p

June 2, 2001

9–15

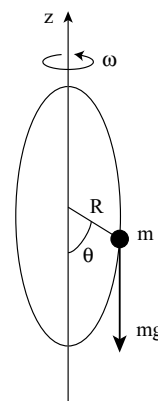
5 problems on 6 hours. Each problem gives a maximum of 5 points.

Write your name on each sheet of paper!

If you want your result by e-mail, write your e-mail address on the first page.

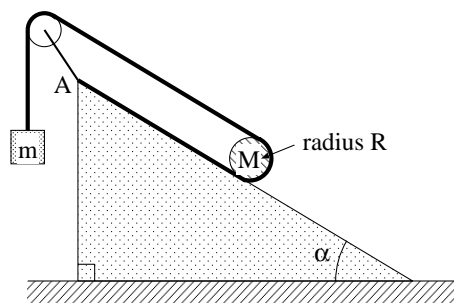
*Allowed books:* Physics Handbook.

1. A mass  $m$  can move without friction along a circular wire (see figure). The wire rotates around the vertical diameter (the  $z$  axis) with a constant angular velocity  $\omega$ . The mass  $m$  is affected by the gravitational force downwards in the figure. Let  $\theta$  be the angle between the vertical direction and the mass  $m$  according to the figure.
  - a) Derive the equation of motion for  $\theta$ . (2p)
  - b) For low angular velocities,  $\theta = 0$  is a stable equilibrium point, whereas it is unstable for high angular velocities. Determine the critical angular velocity  $\omega_c$  that separates these two cases. (2p)
  - c) When  $\omega < \omega_c$ , only  $\theta = 0$  and  $\theta = \pi$  are equilibrium points, whereas when  $\omega > \omega_c$  there is one more equilibrium point. Determine this point! (1p)



**If you have passed on the hand-in exercises, you don't have to do problem 2 below. You will get full points for it anyway.**

2. A homogenous solid cylinder with mass  $M$  and radius  $R$  can roll without friction on a fixed wedge with angle  $\alpha$  (see figure). Around the cylinder, a thin thread (with negligible mass) is wrapped. One end of the thread is attached to the point A, whereas the other end is attached to a mass  $m$ . The thread runs over a frictionless and massless wheel at A. The masses  $m$  and  $M$  are affected by gravity downwards in the figure.



- a) Derive and solve the equation of motion for the mass  $m$ . (3p)
  - b) Determine the angle  $\alpha$  for which the system is in equilibrium. (2p)
3. a) If  $f$ ,  $g$  and  $h$  are functions of the canonical variables, show the following properties for the Poisson brackets,

$$\begin{aligned} \{f, gh\} &= g\{f, h\} + \{f, g\}h \\ \{fg, h\} &= f\{g, h\} + \{f, h\}g \end{aligned} \quad (2p)$$

- b) Consider a particle in three dimensions that move in the potential

$$U = \alpha z^2 e^{\beta x^2 + \gamma y^2} \quad ; \quad \alpha, \beta, \gamma = \text{constants}, \quad \alpha \neq 0.$$

Determine a condition on  $\beta$  and  $\gamma$  such that the  $z$  component of the angular momentum is conserved (for arbitrary initial conditions). (3p)

4. a) Consider the functional

$$I[y] = \int_{x_1}^{x_2} f(y(x), y'(x), x) dx$$

where  $y' = dy/dx$  and  $f$  is a function of  $y$ ,  $y'$  och  $x$ .  $x_1$  and  $x_2$  are two arbitrary (but fixed) end points with  $y(x_1) = y_1$  and  $y(x_2) = y_2$ . Show that if  $I[y]$  assumes an extremum, then  $y$  satisfies Euler's equation for the variational problem,

$$\frac{d}{dx} \left( \frac{\partial f}{\partial y'} \right) - \frac{\partial f}{\partial y} = 0 \quad (3p)$$

- b) Consider two points  $(x_0, y_0)$  and  $(x_1, y_1)$  in the  $xy$  plane. Show that the shortest path between these two points is a straight line. (2p)

*Hint: The line element is given by  $ds = \sqrt{(dx)^2 + (dy)^2} = \sqrt{1 + y'^2} dx$ .*

5. By using a canonical transformation of class B, we can derive the Hamilton-Jacobi equation for the generating function  $S(\underline{q}, \underline{P}, t)$  such that the new Hamiltonian is identically equal to zero.

- a) Show that one, in the same way, can use a transformation of class C with a generating function  $U(\underline{Q}, \underline{p}, t)$  such that the new Hamiltonian is identically equal to zero. Which differential equation does  $U$  have to fulfill? (This equation is called the Hamilton-Jacobi equation in the momentum representation.) (2p)

- b) Use the equation you derived in a) to find the generating function  $U(\underline{Q}, \underline{p}, t)$  for a particle that can move vertically in a homogenous gravitational field, i.e. with the Hamiltonian

$$H = \frac{p^2}{2m} + mgq$$

where  $q$  is the height above the horizontal plane. Then use this  $U$  to generate a canonical transformation which makes the problem trivial to solve. Solve the equations of motion for the new canonical variables and then determine the motion  $\{q(t), p(t)\}$  if the initial conditions are that  $p(t=0) = mv_0$  and  $q(t=0) = 0$ . (3p)

**Good luck!**

*Solutions will eventually be posted as well as be available on  
<http://www.physto.se/~edsjo/teaching/am/index.html>.*

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## Collection of formulae

### Canonical transformations

**Class A.**  $\Phi = \Phi(\underline{q}, \underline{Q}, t)$  - generating function

$$p_i = \frac{\partial \Phi}{\partial q_i} \quad ; \quad P_j = -\frac{\partial \Phi}{\partial Q_j} \quad ; \quad \tilde{H} = H + \frac{\partial \Phi}{\partial t}$$

**Class C.**  $U = U(\underline{Q}, \underline{p}, t)$  - generating function

$$q_i = -\frac{\partial U}{\partial p_i} \quad ; \quad P_j = -\frac{\partial U}{\partial Q_j} \quad ; \quad \tilde{H} = H + \frac{\partial U}{\partial t}$$

**Class B.**  $S = S(\underline{q}, \underline{P}, t)$  - generating function

$$p_i = \frac{\partial S}{\partial q_i} \quad ; \quad Q_j = \frac{\partial S}{\partial P_j} \quad ; \quad \tilde{H} = H + \frac{\partial S}{\partial t}$$

**Class D.**  $V = V(\underline{P}, \underline{p}, t)$  - generating function

$$q_i = -\frac{\partial V}{\partial p_i} \quad ; \quad Q_j = \frac{\partial V}{\partial P_j} \quad ; \quad \tilde{H} = H + \frac{\partial V}{\partial t}$$

### Noether's theorem

If the Lagrangian  $L(\underline{q}, \dot{\underline{q}})$  describes an autonomous system which is invariant under the transformation  $\underline{q} \rightarrow h^s(\underline{q})$  where  $s$  is a real continuous parameter such that  $h^{s=0}(\underline{q}) = \underline{q}$  is the identity transformation, then

$$I(\underline{q}, \dot{\underline{q}}) = \sum_{i=1}^f \frac{\partial L}{\partial \dot{q}_i} \frac{d}{ds} h^s(q_i) \Big|_{s=0}$$

is a constant of motion.