

Total amount of points: 12 p + 2 bp.

## 1 Residue calculus

- (a) (0.5p) Compute the residue in  $z = 0$  of  $f(z) = z^{10} e^{\frac{1}{z^2}}$  and state the type of singularity.
- (b) (1p) Compute the residues in  $z = 0$  and  $z = 2$  of  $h(z) = \frac{\pi \cot(\pi z)}{z-2}$  and state the type of singularity for both points. Mittag-Leffler's theorem might be useful but you can also use another method.

## 2 Integral calculus

- (a) (0.5p) State the two Jordan lemmas. You can refer to them later on, but you will have to detail their application.
- (b) (1p) Change the following real integral into a complex one in order to compute it:

$$I = \int_0^{2\pi} \frac{d\theta}{2 + \cos(\theta) + \sin(\theta)} \quad (1)$$

- (c) (1p) Let  $D_a \cong \{t + ia, t \in \mathbb{R}\}$  be the real line shifted by  $a > 0$  in the upper complex plane. Show that the integral of the Gaussian  $e^{-z^2}$  over  $D_a$  is equal to its integral over the real line and compute its value explicitly:

$$\int_{-\infty}^{+\infty} e^{-(x+ia)^2} dx \equiv \int_{-\infty}^{+\infty} e^{-x^2} dx = ? \quad (2)$$

*Hint:* Apply Cauchy's theorem to the rectangle  $\{(-R, 0), (R, 0), (R, a), (-R, a)\}$  and then take the limit  $R$  goes to infinity.

- (d) (1p) By a principal value calculation similar to the one done for the Dirichlet integral, compute the following integral:

$$J = \int_0^{+\infty} \frac{\sin(x)}{x(x^2 + a^2)} dx \quad \text{for } a \in [0, +\infty[ \quad (3)$$

What happens when  $a = 0$ ? Can you show this without using the explicit result for the integral?

## 3 Primitive calculus

In the book, the following integral is computed thanks a tricky contour.

$$K = \int_0^{+\infty} \frac{dx}{x^3 + 1} \quad (4)$$

The integrand is a rational function so it is actually possible to determine its primitive.

- (a) (1p) Factorize  $x^3 + 1$ ; feel free to use Horner algorithm if you know it. Then decompose  $f(x) = \frac{1}{x^3+1}$  in real partial fractions.
- (b) (2p) Obtain a primitive of  $f(x)$ :

$$F(x) = \int^x f(t) dt = \frac{1}{3} \ln(1+x) - \frac{1}{6} \ln(x^2 - x + 1) + \frac{1}{\sqrt{3}} \arctan\left(\frac{2x-1}{\sqrt{3}}\right) \quad (5)$$

- (c) (1p) Find back the result given in the book by computing limits of  $F(x)$ , namely  $K = \frac{2\pi}{3\sqrt{3}}$ .
- (d) *Bonus:* (1p) calculate  $\int_0^{+\infty} \frac{dx}{x^p+1}$ , where  $p$  is an integer  $p \geq 2$ .

## 4 Kepler's orbits

Consider two point particles with masses  $m_1$  and  $m_2$ , in gravitational interaction. In the course analytical mechanics, you will learn that one can derive the equations of motion from a Lagrangian,  $\mathcal{L} = T - U$ , where  $T$  and  $U$  are the kinetic and potential energy. The Lagrangian of the current system is:

$$\mathcal{L} = \frac{1}{2}m_1\dot{\mathbf{r}}_1^2 + \frac{1}{2}m_2\dot{\mathbf{r}}_2^2 + G\frac{m_1m_2}{|\mathbf{r}_1 - \mathbf{r}_2|} \quad (6)$$

where  $\mathbf{r}_1$  and  $\mathbf{r}_2$  are the position vectors of the particles,  $G$  is the gravitational constant and “ $\dot{\cdot}$ ” means the time derivative. It is one of the very few systems for which the equations of motion can be analytically solved.

- (a) *Bonus:* (1p) In order to decouple the motion of the centre of mass and the relative motion of the particles, perform the following coordinates transformation:

$$\begin{cases} (m_1 + m_2)\mathbf{R} = m_1\mathbf{r}_1 + m_2\mathbf{r}_2 \\ \mathbf{r} = \mathbf{r}_1 - \mathbf{r}_2 \end{cases} \quad (7)$$

Show that the Lagrangian can be written in terms of the new variables as follows:

$$\mathcal{L} = \frac{1}{2}M\dot{\mathbf{R}}^2 + \frac{1}{2}\mu\dot{\mathbf{r}}^2 + \frac{K}{r} \quad (8)$$

with  $M = m_1 + m_2$ ,  $\mu = \frac{m_1m_2}{m_1+m_2}$ ,  $K = GM\mu$  and  $r = |\mathbf{r}|$ .

- (b) (1p) We look for solutions that lie in a plane. Therefore, use the cartesian coordinates  $\mathbf{R} = X\mathbf{e}_x + Y\mathbf{e}_y$  for the center of mass, and polar coordinates  $\mathbf{r} = r\mathbf{e}_r(\theta)$  for the relative motion. We view the relative distance as a function of  $\theta$ .

In deriving the Euler-Lagrange equations, that is, the equations of motion, we view a coordinate and its time derivative as independent, so we write  $\mathcal{L} = \mathcal{L}(q, \dot{q})$ , where  $(q, \dot{q})$  stands for any of the coordinates,  $(X, \dot{X})$ ,  $(r, \dot{r})$  etc. The equations of motion are given by the Euler-Lagrange equations:

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}} = \frac{\partial \mathcal{L}}{\partial q} \quad (9)$$

Obtain the equation of motion for each coordinate  $q$  from the Euler-Lagrange equations. For  $r$ , you should obtain the following 2nd order non-linear ODE:

$$\mu \ddot{r} = \frac{l^2}{\mu r^3} - \frac{K}{r^2} \quad \text{with} \quad l := \mu r^2 \dot{\theta} \equiv \text{constant}. \quad (10)$$

What is the motion of the center of mass? What is the physical interpretation of  $l$ ?

- (c) (1p) Perform the transformation  $u = \frac{1}{r}$  with  $u$  seen as a function of  $\theta$  (instead of time) and apply the chain rule to the differential operator:  $\frac{d}{dt} = \frac{d\theta}{dt} \frac{d}{d\theta}$ . The expressions for the velocity and acceleration in terms of  $u$  are known as Binet's formulae.
- (d) (1p) Solve the equation for  $u(\theta)$  and conclude on the possible orbits in the center of mass frame.